

# CSE 120

## Principles of Operating Systems

Winter 2007

### Lecture 2: Architectural Support for Operating Systems

Keith Marzullo and Geoffrey M. Voelker

## Administrivia

---

- **Mailing list**
  - ◆ You should be getting mail on the list. If not, let me know.
- **Homework #1**
  - ◆ Due 1/18
- **Project 0**
  - ◆ Due 1/18
  - ◆ Done individually
- **Project groups**
  - ◆ Send your group info to Jeremy and Michael (jl@cs.ucsd.edu, mvrable@cs.ucsd.edu)

## Why Start With Architecture?

---

- Operating system functionality fundamentally depends upon the architectural features of the computer
  - ◆ Key goals of an OS are to enforce **protection** and **resource sharing**
  - ◆ If done well, applications can be oblivious to HW details
  - ◆ Unfortunately for us, the OS is left holding the bag
- Architectural support can greatly simplify – or complicate – OS tasks
  - ◆ Early PC operating systems (DOS, MacOS) lacked virtual memory in part because the architecture did not support it
  - ◆ Early Sun 1 computers used two M68000 CPUs to implement virtual memory (M68000 did not have VM hardware support)

## Architectural Features for OS

---

- Features that directly support the OS include
  - ◆ Protection (kernel/user mode)
  - ◆ Protected instructions
  - ◆ Memory protection
  - ◆ System calls
  - ◆ Interrupts and exceptions
  - ◆ Timer (clock)
  - ◆ I/O control and operation
  - ◆ Synchronization

## Types of Arch Support

---

- Manipulating privileged machine state
  - ◆ Protected instructions
  - ◆ Manipulate device registers, TLB entries, etc.
- Generating and handling “events”
  - ◆ Interrupts, exceptions, system calls, etc.
  - ◆ Respond to external events
  - ◆ CPU requires software intervention to handle fault or trap
- Mechanisms to handle concurrency
  - ◆ Interrupts, atomic instructions

## Protected Instructions

---

- A subset of instructions of every CPU is restricted to use only by the OS
  - ◆ Known as protected (privileged) instructions
- Only the operating system can
  - ◆ Directly access I/O devices (disks, printers, etc.)
    - » Security, fairness (why?)
  - ◆ Manipulate memory management state
    - » Page table pointers, page protection, TLB management, etc.
  - ◆ Manipulate protected control registers
    - » Kernel mode, interrupt level
  - ◆ Halt instruction (why?)

## OS Protection

---

- How do we know if we can execute a protected instruction?
  - ♦ Architecture must support (at least) two modes of operation: **kernel** mode and **user** mode
    - » VAX, x86 support four modes; earlier archs (Multics) even more
    - » Why? Protect the OS from itself (software engineering)
  - ♦ Mode is indicated by a status bit in a protected control register
  - ♦ User programs execute in user mode
  - ♦ OS executes in kernel mode (OS == “kernel”)
- Protected instructions only execute in kernel mode
  - ♦ CPU checks mode bit when protected instruction executes
  - ♦ Setting mode bit must be a protected instruction
  - ♦ Attempts to execute in user mode are detected and prevented

January 11, 2007

CSE 120 – Lecture 2 – Architectural Support for OSes

7

## Memory Protection

---

- OS must be able to protect programs from each other
- OS must protect itself from user programs
- May or may not protect user programs from OS
- Memory management hardware provides memory protection mechanisms
  - ♦ Base and limit registers
  - ♦ Page table pointers, page protection, TLB
  - ♦ Virtual memory
  - ♦ Segmentation
- Manipulating memory management hardware uses protected (privileged) operations

January 11, 2007

CSE 120 – Lecture 2 – Architectural Support for OSes

8

# Events

---

- An event is an “unnatural” change in control flow
  - ◆ Events immediately stop current execution
  - ◆ Changes mode, context (machine state), or both
- The kernel defines a handler for each event type
  - ◆ Event handlers always execute in kernel mode
  - ◆ The specific types of events are defined by the machine
- Once the system is booted, all entry to the kernel occurs as the result of an event
  - ◆ In effect, the operating system is one big event handler

# Categorizing Events

---

- Two kinds of events, **interrupts** and **exceptions**
- Exceptions are caused by executing instructions
  - ◆ CPU requires software intervention to handle a fault or trap
- Interrupts are caused by an external event
  - ◆ Device finishes I/O, timer expires, etc.
  
- Two reasons for events, **unexpected** and **deliberate**
- Unexpected events are, well, unexpected
  - ◆ **What is an example?**
- Deliberate events are scheduled by OS or application
  - ◆ **Why would this be useful?**

## Categorizing Events (2)

- This gives us a convenient table:

	Unexpected	Deliberate
Exceptions (sync)	fault	syscall trap
Interrupts (async)	interrupt	software interrupt

- ♦ Terms may be used slightly differently by various OSes, CPU architectures...
- ♦ Software interrupt – a.k.a. async system trap (AST), async or deferred procedure call (APC or DPC)
- Will cover faults, system calls, and interrupts next
  - ♦ Does anyone remember from CSE 141 what a software interrupt is?

## Faults

- Hardware detects and reports “exceptional” conditions
  - ♦ Page fault, unaligned access, divide by zero
- Upon exception, hardware “faults” (verb)
  - ♦ Must save state (PC, regs, mode, etc.) so that the faulting process can be restarted
- Modern OSes use VM faults for many functions
  - ♦ Debugging, distributed VM, GC, copy-on-write
- Fault exceptions are a performance optimization
  - ♦ Could detect faults by inserting extra instructions into code (at a significant performance penalty)

# Handling Faults

---

- Some faults are handled by “fixing” the exceptional condition and returning to the faulting context
  - ◆ Page faults cause the OS to place the missing page into memory
  - ◆ Fault handler resets PC of faulting context to re-execute instruction that caused the page fault
- Some faults are handled by notifying the process
  - ◆ Fault handler changes the saved context to transfer control to a user-mode handler on return from fault
  - ◆ Handler must be registered with OS
  - ◆ Unix **signals** or NT **user-mode Async Procedure Calls (APCs)**
    - » SIGALRM, SIGHUP, SIGTERM, SIGSEGV, etc.

# Handling Faults (2)

---

- The kernel may handle unrecoverable faults by killing the user process
  - ◆ Program fault with no registered handler
  - ◆ Halt process, write process state to file, destroy process
  - ◆ In Unix, the default action for many signals (e.g., SIGSEGV)
- What about faults in the kernel?
  - ◆ Dereference NULL, divide by zero, undefined instruction
  - ◆ These faults considered fatal, operating system crashes
  - ◆ **Unix panic**, **Windows “Blue screen of death”**
    - » Kernel is halted, state dumped to a core file, machine locked up

# System Calls

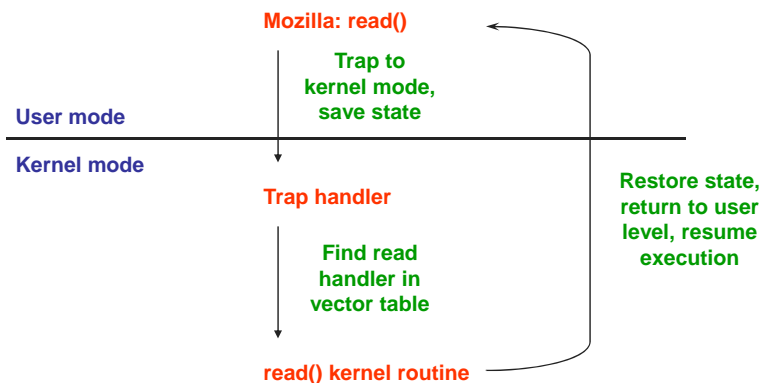
- For a user program to do something “privileged” (e.g., I/O) it must call an OS procedure
  - ♦ Known as **crossing the protection boundary**, or a **protected procedure call**
- Arch provides a **system call** instruction that:
  - ♦ Causes an exception, which vectors to a kernel handler
  - ♦ Passes a parameter determining the system routine to call
  - ♦ Saves caller state (PC, regs, mode) so it can be restored
    - » **Why save mode?**
  - ♦ Returning from system call restores this state
- Requires architectural support to:
  - ♦ Verify input parameters (e.g., valid addresses for buffers)
  - ♦ Restore saved state, reset mode, resume execution

January 11, 2007

CSE 120 – Lecture 2 – Architectural Support for OSes

15

# System Call



January 11, 2007

CSE 120 – Lecture 2 – Architectural Support for OSes

16

## System Call Questions

---

- What would happen if the kernel did not save state?
- What if the kernel executes a system call?
- What if a user program returns from a system call?
- How to reference kernel objects as arguments or results to/from system calls?
  - ◆ A naming issue
  - ◆ Use integer object handles or descriptors
    - » E.g., Unix file descriptors
    - » Only meaningful as parameters to other system calls
  - ◆ Also called capabilities (more later when we do protection)
  - ◆ Why not use kernel addresses to name kernel objects?

## Interrupts

---

- Interrupts signal asynchronous events
  - ◆ I/O hardware interrupts
  - ◆ Software and hardware timers
- Two flavors of interrupts
  - ◆ Precise: CPU transfers control only on instruction boundaries
  - ◆ Imprecise: CPU transfers control in the middle of instruction execution
    - » What does that mean?
  - ◆ OS designers like precise interrupts, CPU designers like imprecise interrupts
    - » Why?

# Timer

---

- The timer is critical for an operating system
- It is the fallback mechanism by which the OS reclaims control over the machine
  - ♦ Timer is set to generate an interrupt after a period of time
    - » Setting timer is a privileged instruction
  - ♦ When timer expires, generates an interrupt
  - ♦ Handled by kernel, which controls resumption context
    - » Basis for OS [scheduler](#) (*more later...*)
- Prevents infinite loops
  - ♦ OS can always regain control from erroneous or malicious programs that try to hog CPU
- Also used for time-based functions (e.g., *sleep()*)

# I/O Control

---

- I/O issues
  - ♦ Initiating an I/O
  - ♦ Completing an I/O
- Initiating an I/O
  - ♦ Special instructions
  - ♦ Memory-mapped I/O
    - » Device registers mapped into address space
    - » Writing to address sends data to I/O device

## I/O Completion

---

- Interrupts are the basis for asynchronous I/O
  - ◆ OS initiates I/O
  - ◆ Device operates independently of rest of machine
  - ◆ Device sends an interrupt signal to CPU when done
  - ◆ OS maintains a vector table containing a list of addresses of kernel routines to handle various events
  - ◆ CPU looks up kernel address indexed by interrupt number, context switches to routine
- If you have ever installed earlier versions of Windows, you now know what IRQs are for

## I/O Example

---

1. Ethernet receives packet, writes packet into memory
2. Ethernet signals an interrupt
3. CPU stops current operation, switches to kernel mode, saves machine state (PC, mode, etc.) on kernel stack
4. CPU reads address from vector table indexed by interrupt number, branches to address (Ethernet device driver)
5. Ethernet device driver processes packet (reads device registers to find packet in memory)
6. Upon completion, restores saved state from stack

## Interrupt Questions

---

- Interrupts halt the execution of a process and transfer control (execution) to the operating system
  - ♦ Can the OS be interrupted? (Consider why there might be different IRQ levels)
- Interrupts are used by devices to have the OS do stuff
  - ♦ What is an alternative approach to using interrupts?
  - ♦ What are the drawbacks of that approach?

## Synchronization

---

- Interrupts cause difficult problems
  - ♦ An interrupt can occur at any time
  - ♦ A handler can execute that interferes with code that was interrupted
- OS must be able to synchronize concurrent execution
- Need to guarantee that short instruction sequences execute atomically
  - ♦ Disable interrupts – turn off interrupts before sequence, execute sequence, turn interrupts back on
  - ♦ Special atomic instructions – read/modify/write a memory address, test and conditionally set a bit based upon previous value
    - » XCHG on x86

# Summary

---

- Protection
  - ◆ User/kernel modes
  - ◆ Protected instructions
- System calls
  - ◆ Used by user-level processes to access OS functions
  - ◆ Access what is “in” the OS
- Exceptions
  - ◆ Unexpected event during execution (e.g., divide by zero)
- Interrupts
  - ◆ Timer, I/O

# Next Time...

---

- Read Chapter 4 (Processes)
- Homework #1
- Project 0